



EX-II EUCUS

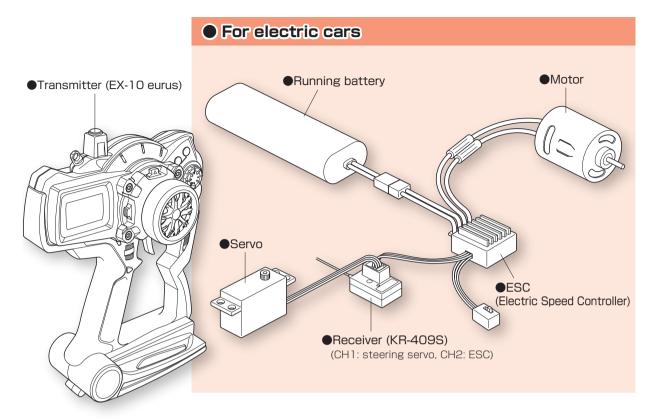
Instruction manual

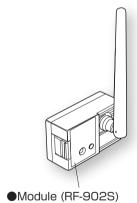
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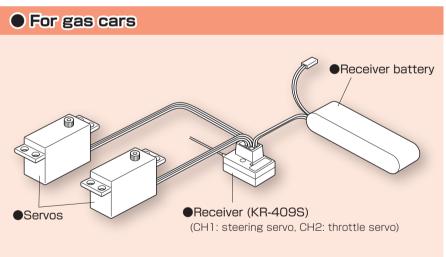
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■ Receiver installation







Caufion! When using units not included in the set, be sure to use only compatible products. Please refer to our website for details (www.kopropo.co.jp)

■ For safe operation

Read carefully and fully understand the following instructions for safety use.

With the nature of radio controlled model, improper usage may result in serious accidents. In order to avoid these circumstances, please read following contents before use. We cannot be held responsible for problems encountered when not complying with these cautions and notices.

Warning! Failure to observe the matter discussed in such an item poses a serious threat of death or severe injury.

Caution! Failure to observe the matter discussed in such an item poses a possibility of injury or damage to the equipment or property.

Caution when installing units

•Make sure metal parts do not come in direct contact to model (chassis/ship hull) by vibration.

Noise of metal parts may result in malfunction of receiver, and the model may run out of control.

Do not cut nor bundle receiver antenna with other cables.

*It may result in decreasing the sensitivity of receiver and may result in the model running out of control.

■Note polarity when installing batteries to transmitter and receiver.

*It may damage R/C units.

•Be sure to connect receiver, servo and switch connectors correctly.

*If connections are loosened by vibration, the model may run out of control.

 Attach receiver using thick double-sided tape to avoid direct contact with other parts.

*Strong shock and vibration may result in the model running out of control.

•Operate servo to check that there are no unnecessary forces onto the push rod. *It may damage the servo or increase the consumption of batteries.

■Make sure to use rubber grommet to attach servo and be sure that the servo is not touching mechanism plate directly.

*The vibration may damage the servo and the model may run out of control.

•Use genuine KO transmitter, receiver, servo, speed controller and optional parts.

*We cannot be held responsible for problems encountered when using with other maker's products...

Notes on driving

Do not use in thunderstorms.

*There is possibility of lightning striking the antenna.

•Do not use in the rain or in a location where water might get in.

%The unit may become wet in and run out of control.

Do not use in the following places.

1. Near to other radio control circuits (within 3km).

2. Near to people or on the street.

3. Near electric wires or communication facilities.

In the case of the model running out of control, dangerous situations will occur.

Do not run the model when you experience difficulties in concentration through tiredness, alcohol or medication.

*The miss-judgment may result in accidents.



Warning!

Prohibited matters

Warning!

Prohibited matters

• Warning! Prohibited matters

●Do not allow fuel or exhaust to touch plastic parts. **It may attack plastic.



- Make sure that model memory is matched to the model currently running.
 *Otherwise, it may cause car to run out of control.
- •Make sure to stop engine (disconnect motor cables) before making function change.

Caution! Prohibited matters

- Do not touch engine, motor or speed controller immediately after running.
 *They are hot and can cause burns.
- Always turn on the transmitter first, followed by the receiver. When turning off, turn off the receiver first, followed by the transmitter.
- *If you don't follow the order, receiver may get interference and run out of control.

Caution! Enforcement matters

- Dismantling of transmitter is prohibited and it can be punished. Disassembly and modification of all units may cause accidents such as a short circuit. Also, repair service may not be accepted in this case.
- Do not use in aircraft, hospital or near electrical equipment such as fire alarm or medical equipment. It may cause malfunction and result in serious accidents. Turn off the transmitter immediately if it effects on other wireless or electric appliances.

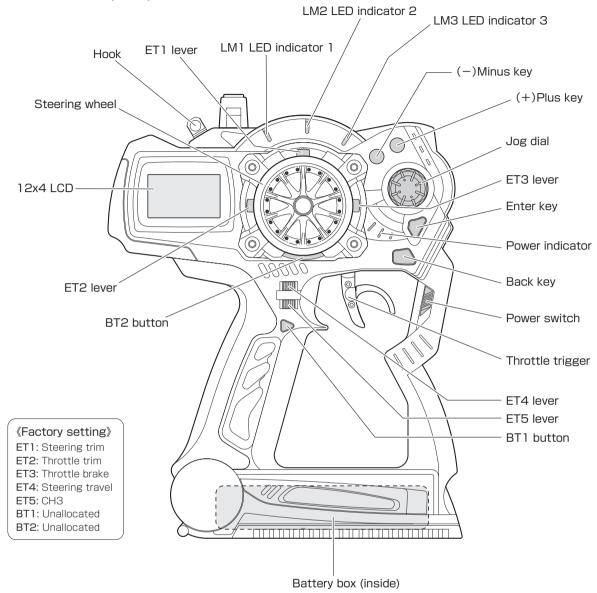
Notes after driving

• Warning! Enforcement matters

- ■When using with electric powered R/C car, make sure to remove batteries after running.
- *If the power turns on accidentally, it may cause the model to run out of control or fire disaster.
- •Keep transmitter, batteries and model out of reach of children.
- *Chemical material may cause personal injury.
- •Remove batteries from transmitter when not in use for a long time.
- If you leave batteries in the transmitter, leakage may damage transmitter.
- Avoid storing transmitter and receiver in the following places.
 - 1. Extremely hot or cold places (+40°C or -10°C).
- <u>(1)</u> Caution! Enforcement matters
- 2. Under direct sunlight.
- 3. High humidity places.
- 4. Vibration.
- 5. Dusty places.
- If you store the unit under these circumstances, it may result in deformation or damage to the unit.

■ Name of parts

Transmitter (front)

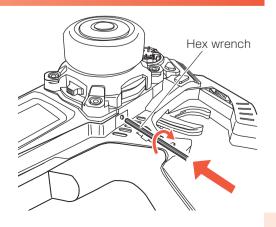


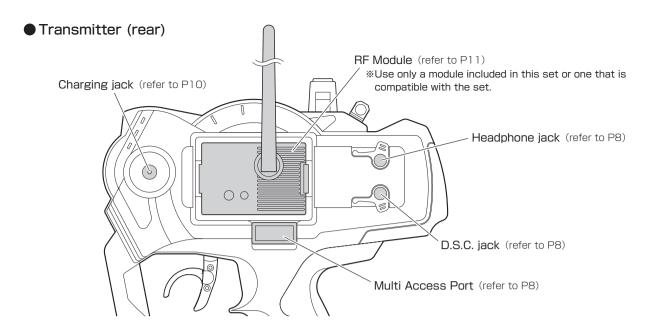
Adjustment of steering tension

By changing spring damper in the steering wheel, steering tension can be adjusted.

《Tech tip》

Insert hex wrench (1.5mm) as shown and rotate it to the right (clockwise) for stronger tension. Rotate it to the left (counter-clockwise) for weaker tension.





D.S.C. jack

By connecting receiver and servo directly with transmitter using D.S.C. (Direct Servo Control), you can configure settings without transmitting radio wave in pit area or near R/C circuit (D.S.C. cable (optional available) required).

- 1. Turn off transmitter and remove rubber cover from D.S.C. jack. Connect D.S.C. cable (transmitter will be turned on automatically).
- **2.** (For KR-409S receiver) Press both +/- keys to choose Digital mode (see P25). (For PPM receivers) Choose response mode NORM, HSP or ADV (see P25).
- (For PPM receivers) Choose response mode NORM, HSP or ADV (see P25).

 3. Connect D.S.C. cable to battery channel in receiver.

 (Receiver) Battery channel
- 4. Connect receiver with battery using the channel not employed (such as CH3).
- **5.** Connect servo with receiver and set up.

Caution! Remove crystal from receiver before connecting.

6. Disconnect battery from receiver first, and then detach D.S.C. cable from transmitter.

Multi Access Port

Connecting Data Pack (optional available) or ICS Communication Adaptor/ICS USB Adaptor (optional available) using Multi Access Port will allow for more fine data management.

[Data Pack (optional available)] Extra 10 model memories are available (refer to P17).

[ICS Communication Adapter/ICS USB Adapter (optional available)]

Allows for fine data controlling using a PC.

Headphone jack

A jack for headphone/earphone (\$\Phi 3.5mm / separately available).

*During headphone or earphone connected, beeps from transmitter are effective. Headphone jack is monaural output.

Adjustment of steering wheel and throttle trigger

(Steering wheel spacer)

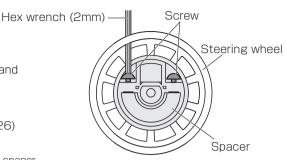
Reduces movable range of steering wheel.

《Tech tip》

- **1** Detach steering sponge from steering wheel.
- **2.** Insert hex wrench (2mm) as shown. Tighten both right and left screws to adjust movable range.
- 3. Re-attach steering sponge.
- **4.** Adjust steering angle using volume adjustment (see P26) to maintain maximum steering angle.

*Initial setting: Tip of screw's face is flush with the inside of the spacer.

《Steering wheel (inside)》



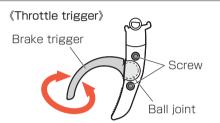
[Multi-angle 3D adjustable trigger]

Freely adjust brake and throttle trigger's position and angle.

《Tech tip》

- Loosen screws using hex wrench (1.5mm).
- 2. Freely adjust brake trigger.
- **3.** Tighten screws to fix brake trigger.

*The trigger may be loosened by temperature, strong shock or after long use. To avoid the trigger loosened, gluing is also effective.



(Steering wheel extension unit)

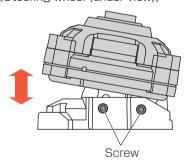
Mounting angle of steering wheel can be adjusted.

*Attach on transmitter (refer to manual included in set for installation).

《Tech tip》

- 1. Loosen screws under steering wheel extension unit using hex wrench (3mm) as shown.
- 2. Adjust mounting angle.
- 3. Tighten screws to fix.

(Steering wheel (under view))



Replacement of color pad and grip (option)

Color pad and grip are optional available.

《Detachment》

Extend grip end outward (1) and pull out (2).

Pull out pad toward the arrowed direction (3),

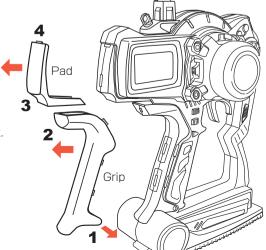
then detach tab (4).

(Attachment)

Attach pad and grip in the reverse procedures of detachment.

Attach tab (4), then insert pad end (3).

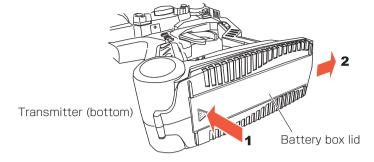
Attach grip by inserting tabs (2) and insert grip end (1).



■ Unit preparation

Battery installation

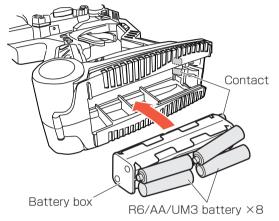
1. Slide battery box lid, pressing triangle on the lid.



2. Install R6/AA/UM3 batteries ×8 in the battery box. Note contact points.

*Note polarity and use fresh batteries. Depleted batteries may deteriorate radio power and cause malfunction.

Caufion! Do not use high voltage dry batteries (such as Lithium) because the voltage is too high and may damage the transmitter.



[Battery Pack (optional available)]

A chargeable battery pack (optional available)

《Installation》

Connect battery cable and store it in transmitter. *Apply buffer sponge on battery box lid inside.

Caution!

Be sure not to miss polarity of battery pack.

Be sure to connect battery cable correctly when using battery pack other than KO genuine products. Always refer to the illustration in the manual before battery installation.

《Charging》

Connect KO genuine AC100V charger or DC12V quick charger with charging jack as shown.

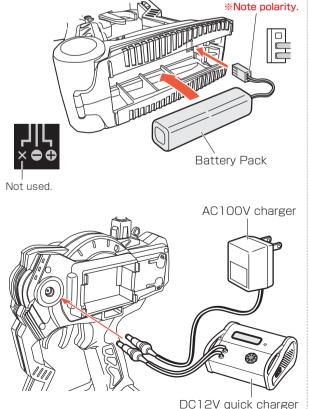
**For AC100V charger, charge battery pack for 14-18 hours after discharged.

Caufion! Never charge R6/AA/UM3 batteries through transmitter. It will occur leakage or burst, leading to serious damage of transmitter.

Caufion! When discharging battery pack, always remove it from transmitter (do not discharge using charging jack).

Caution! Be careful that charging current does not exceed 1A.

Caufion! Read carefully and fully understand instruction manual included in battery pack.



Attachment and replacement of module

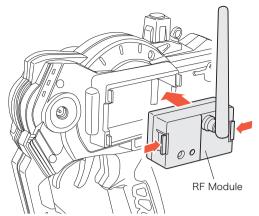
Attach module as shown. When detaching, press both side of tabs on the module and pull out module.

**For frequency change (2.4GHz, 27MHz, 40MHz), replace module.

Caution! Turn off transmitter before module replacement.

Caufion! Attach retractable antenna (optional available) when using frequency 27MHz or 40MHz.

Caufion! Refer to instruction manual included in module.



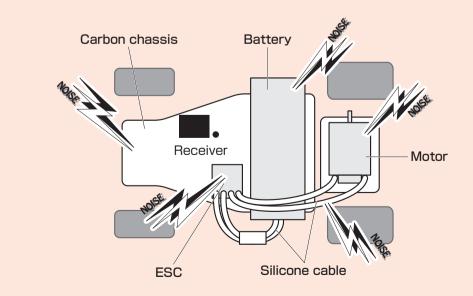
■ Notes on installing receiver (anti-noise measures)

Keep antenna cable far away from noise source!



Assume that all areas where large currents are flowing are generating noise! Locate antenna cable and receiver as far away from the motor, ESC, silicone cables as possible (material such as metal or carbon chassis also conduct noise).

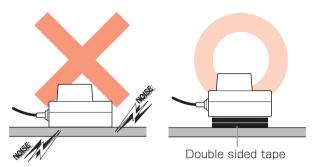
R/C model is controlled by radio wave. Therefore, anti-noise measure is the most important factor. Take measures to ensure optimum performance of your R/C model and driving technique.



Receiver installation on carbon chassis

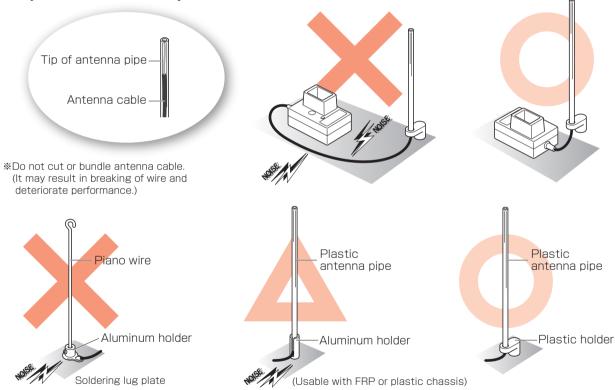
When fixing the receiver to the chassis or on the mechanism deck, use more than 2 layers of double-sided tape to avoid direct contact with chassis. Chassis and mechanism deck (especially carbon material) can also conduct noise. Making space between receiver with them is recommend to ensure protection against noise.

*Note receiver's LED position when installing.



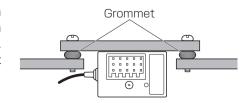
Antenna installation

Raise antenna cable vertically and set as high as possible. Pass cable into antenna pipe to protect from damage. Make the tip of antenna cable aligned with antenna pipe end. Installing antenna holder far away from receiver may deteriorate radio sensitivity. Locate antenna holder as near to the receiver as possible. Make sure that the antenna cable does not come in direct contact with chassis, mechanism plate or other noise sources. Make sure to use plastic antenna pipe and mount. Do not use metal antenna mount as it easily conducts noise and may cause troubles.



Attaching to a gas car

Engine vibration may damage the receiver. Make sure to attach grommet (receiver holder) to reduce vibration. Do not attach directly to chassis or mechanism plate using double-sided tape. The installation position should be as far as possible from heat from engine or exhaust.



*Note receiver's LED position when installing.

Installation and setting of R/C units

1. Install and connect receiver, servo and ESC (for electric car) to your R/C car. Be careful and note the anti-noise measures (refer to P11).

*Read instruction manual included in servo and ESC carefully.

- 2. Install battery in transmitter and attach module (refer to P10-11). Then, install running battery for an electric car or install receiver battery for a gas car.
- **3.** Register receiver to transmitter (pairing/see below).

**Before using a receiver for the first time, pairing is required.

If you several receivers for one transmitter, pair is also required for each receiver when used for the first time.

- 4. Adjust steering, throttle and brake (refer to P18-24).
- **5.** Set fail-safe function (see below).

*If R/C model runs out of control (in case receiver loses radio wave from transmitter), the fail-safe function will keep throttle (CH2) to brake or neutral position for safety use.

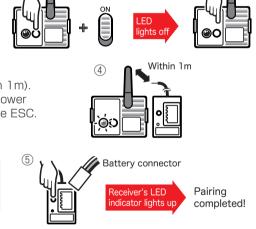
(How to pair)

- Attach module (RF-902S) to transmitter and raise antenna.
- ② Keep pressing set button of the module and turn transmitter on (LED on module will light up).
- ③ After approx. 3 seconds, LED will light off. Then release set button (LED will be dim and ready for pairing).
- (4) Move receiver antenna close to transmitter (approx. within 1 m).
- (5) Hold the set button of the receiver and turn the receiver power ON by either connecting the battery cable or turning on the ESC.
- ® Release the set button and receiver's LED will be solid. Turn off the receiver and transmitter to save the pairing.

Operation check:

Turn on transmitter and check if LED on module lights up. Then turn on receiver and check if receiver's LED lights up.

**Try pairing later or in another location if someone is pairing near by. WiFi and microwaves also affect pairing.



*Check operation by turning OFF the receiver, transmitter and then turning ON the transmitter and receiver.

(Setting fail-safe function)

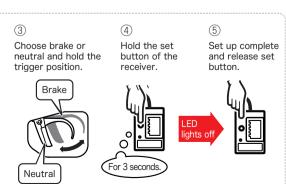
- (1) Turn on transmitter.
- 2 Turn on receiver. Check if servo operates correctly.
- ③ Keep throttle trigger in brake or neutral position.
- (4) Hold the set button on the receiver for 3 seconds.
- (5) After the receiver's LED indicator goes off, release the set button.

Operation check:

Turn on transmitter and receiver. Then turn off transmitter and check if fail-safe function is effective.

*For safety use, please set fail-safe function.

**For gas car, reset fail-safe function if the brake linkage is changed.
If not reset, the former setting will be used and may not be correct.



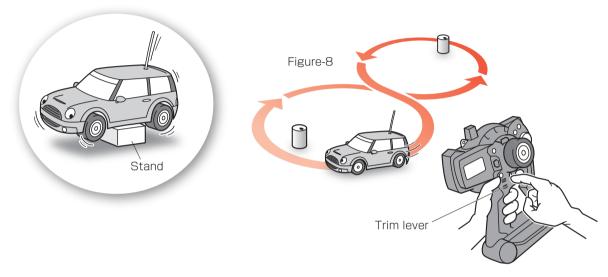
**Check operation by turning OFF the receiver, transmitter and then turning ON the transmitter and receiver.

■ Procedure when running

1. Power on: Note surroundings and switch transmitter on, then switch receiver on.

*EX-10 eurus automatically finds unused frequency band after switching on. This function is called "carrier sense". To perform carrier sense effectively, switch the transmitter on around the running area as close as possible.

- **2.** Checking model: Watch and check model to be used.
- **3.** Checking movements: Raise wheels from ground and operate transmitter to check movements. Detail adjustment using steering/throttle trim lever should be done while running. Adjust steering balance by performing figure-8.



4. Power off: Turn OFF receiver, transmitter and remove car battery.

*Make sure to switch the transmitter on and off in an interval of at least 5 seconds.



Functions

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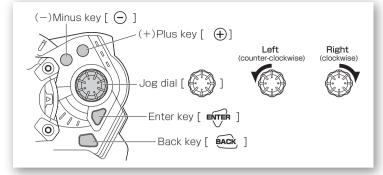
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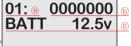
Start menu

Start menu for each function setting.



Power ON!





01:

01:

BATT

BATT



0000000

12.5v

ENTER

BACK

ENTER

BACK

(Start menu)

- a: Current model memory's number
- **b**: Current model memory's name
- ©: Voltage **"LOW BATT" blinked when under 9.0V.
- Optional function (refer to P27).

[Model menu] (P.17)



Model control functions.

The model indicates a program with proper settings for each condition.

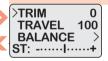


0000000

12.5v

MD ST TH OP

[Steering menu] (P.18~20)



Steering control functions.





MD >ST TH OP

[Throttle menu] (P.21~24)





>TRIM 0 HPOINT F100 BRAKE B100 TH: -------+

Throttle control functions.



(Option menu) (P.25~29)







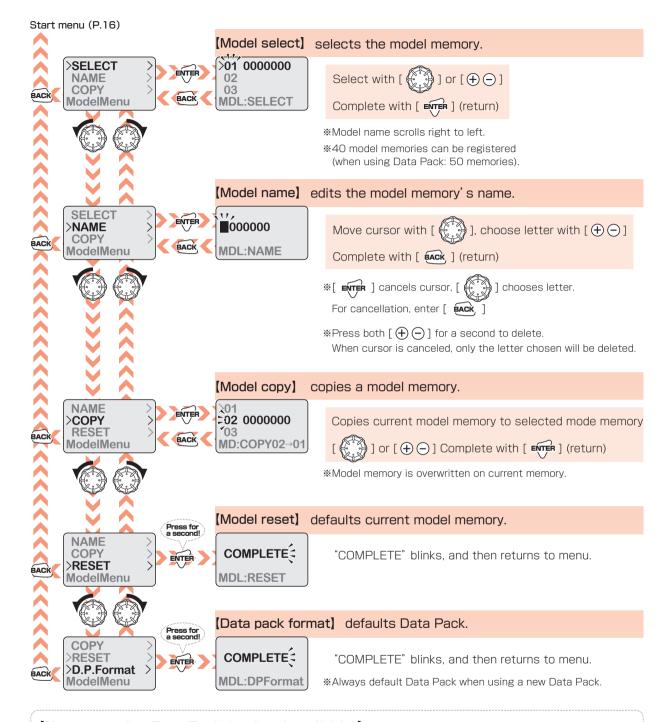
>CH3 > CH4 > RSP NORMAL OptionMenu

Other optional setting functions.

Model menu



Model control functions. The model indicates a program with proper settings for each condition.



(Notes on using Data Pack (optional available))

By employing Data Pack (optional available), extra 10 model memories are available in addition to inner 40 memories (model memories will be numbered from 41-50).

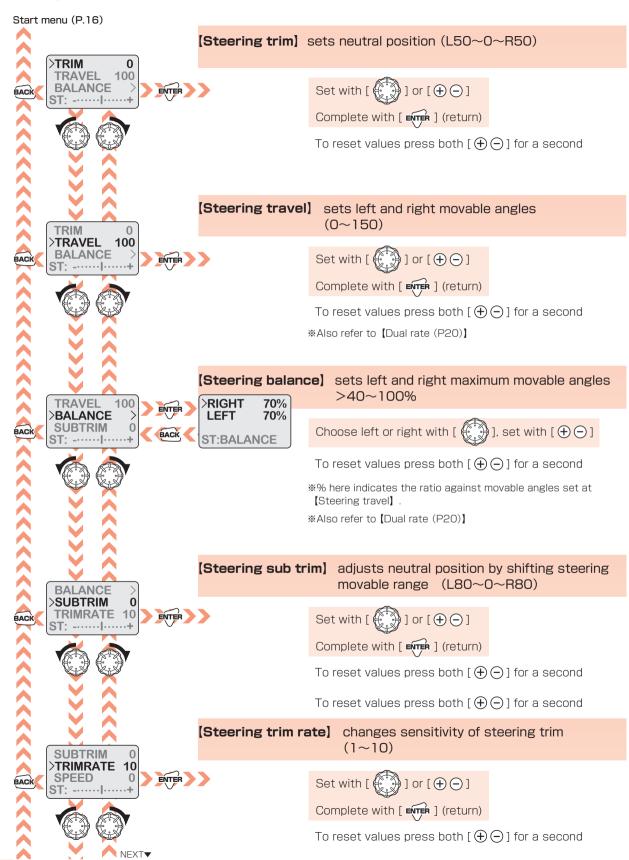
《Connecting Data Pack》

- Connect Data Pack with Multi Access Port (refer to P8).
- Be sure to attach/detach Data Pack while transmitter turned off.
- If the Data Pack is removed while the transmitter is turned on, alarm sounds and model menu switches to "model select".
 Choose inner model memory (1-40) immediately.

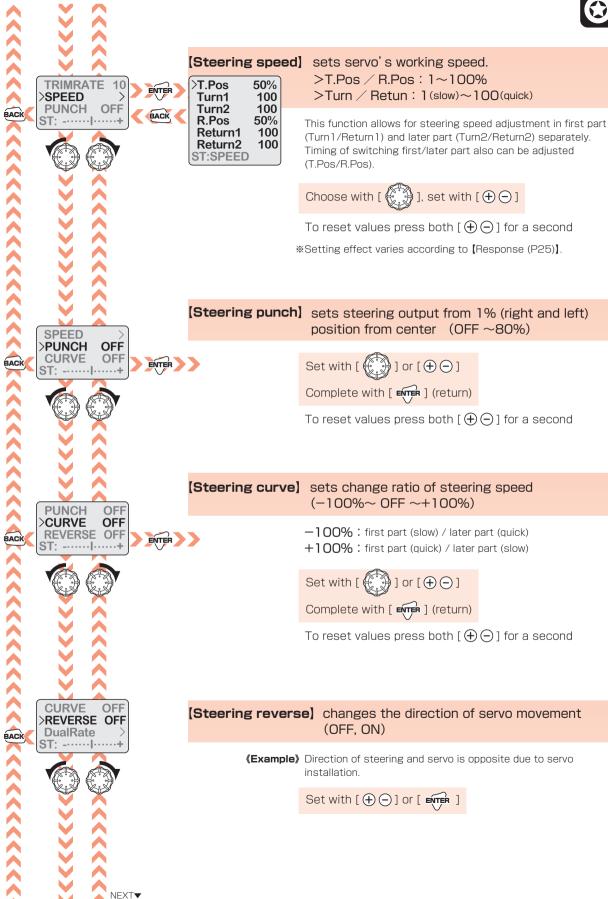
Steering menu



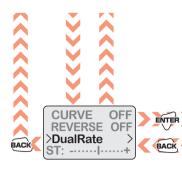
Steering control functions.











[Dual rate]

TRAVEL

ST:DualRate

BLC.L

BLC.R

100

70%

70%

changes steering travel and balance while running. >KEY(allocates function key): OFF, ET1~5, BT1, BT2 >KEY **OFF BUTTON TGLE**

>BUTTON:

TGLE(switches [dual rate] by pressing function key), PUSH([dual rate] is effective during holding function key)

>TRAVEL: 0~150

>BLC.L(for left balance): 40~100% >BLC.R(for right balance): 40~100%

(Example) Straight (smaller TRAVEL), low speed corner (larger TRAVEL).



To reset values press both [\bigoplus \bigcirc] for a second

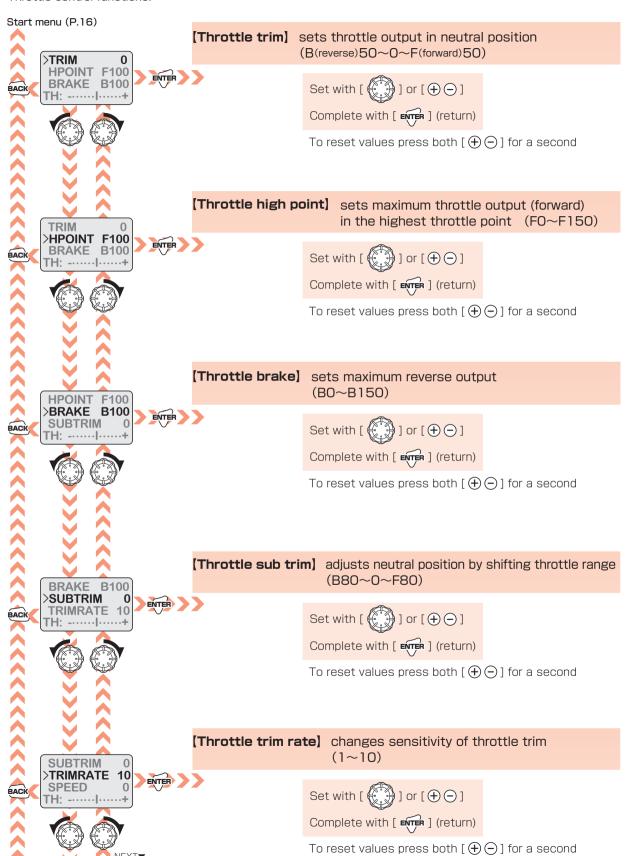
*Press or hold function key while running.

*Also refer to [Steering travel (P18)] and [Steering balance (P18)] .

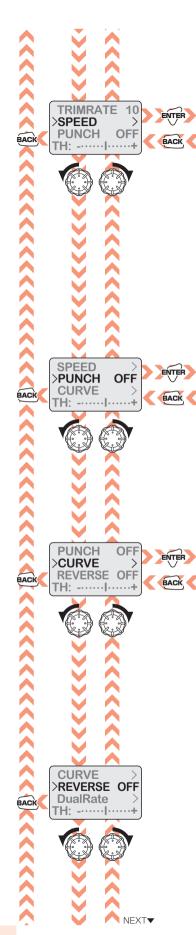
Throttle menu

T

Throttle control functions.







>Tr.L→M 30% Tr.M→H 80% 100 TurnL TurnM 100 100 TurnH Rt.H→M 80% $Rt.M \rightarrow L$ 30% ReturnH 100 ReturnM 100 ReturnL 100 TH:SPEED

(Throttle speed) sets throttle response (forward).

>Tr.L/Tr.M \rightarrow M/H, Rt.H/Rt.M \rightarrow M/L: 1 \sim 100% >TurnL/M/H, ReturnH/M/L: 1(slow)~100(fast)

This function allows for throttle response adjustment (forward) in slow range (TurnL/ReturnL), mid range (TurnM/ReturnM) and high range (TurnH/ReturnH) independently. Switching point (Tr.L \rightarrow M/Rt.M \rightarrow L) and (Tr.M \rightarrow H/Rt.M \rightarrow H) are also adjustable. (Turn: acceleration, Return: deceleration)



Choose with $[\bigoplus]$, set with $[\bigoplus \bigcirc]$

To reset values press both [(+) (-)] for a second

>FWD **OFF** ÖFF **BACK** TH:PUNCH

[Throttle punch] adjust throttle response around neutral position.

>FWD(forward) / BACK(reverse) : OFF ~80%



Choose with $[\ \ \ \ \ \ \]$, set with $[\ \ \ \ \ \ \]$

To reset values press both [(+) (-)] for a second

[Throttle curve]

>FWD **OFF BACK** OFF

TH:CURVE

sets change ratio of throttle speed.

>FWD(forward) / BACK(reverse) :-100%~OFF~+100%

-100%: first part (slow) / later part (quick) +100%: first part (quick) / later part (slow)



Choose with $[(\bigcirc)]$, set with $[\bigcirc)$

To reset values press both [(+) (-)] for a second

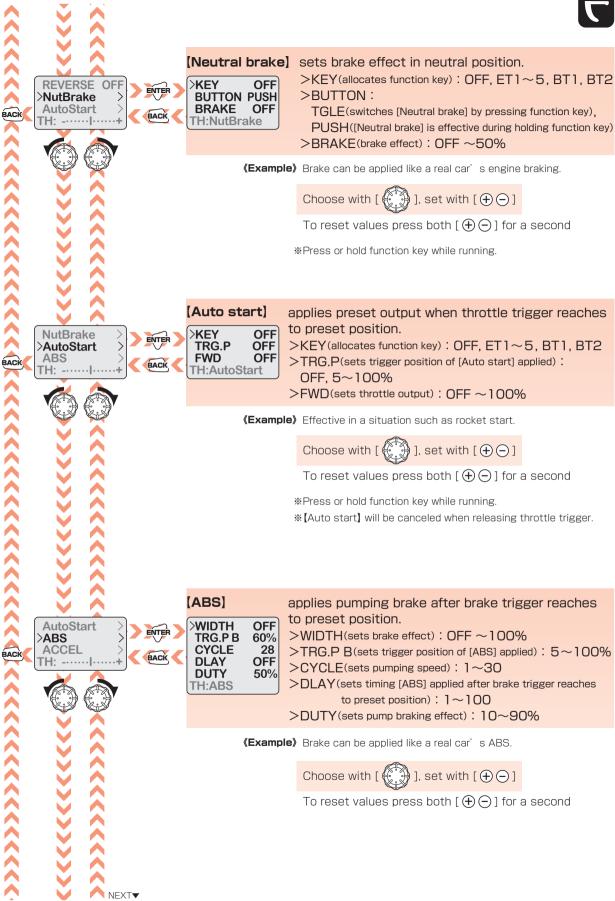
*[Throttle punch] and [Throttle curve] have synergistic effect.

[Throttle reverse] changes the direction of throttle movement (OFF, ON)

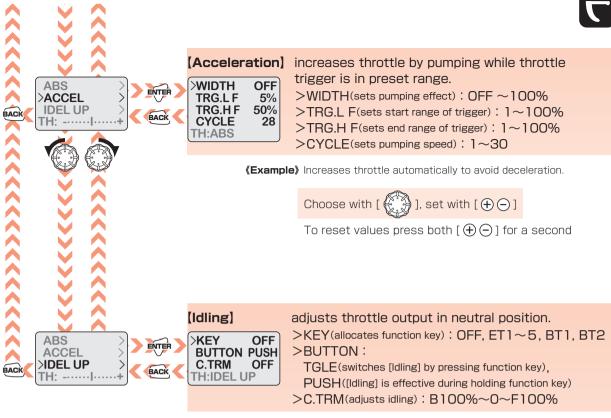
> **(Example)** Direction of throttle and servo is opposite due to servo installation.

> > Set with [+ -] or [ENTER]









(Example) Effective for a gas car when fueling.

Choose with [), set with [)

To reset values press both [(+) (-)] for a second

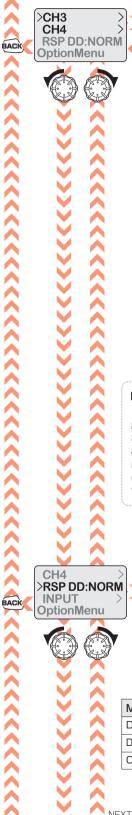
*Press or hold function key while fueling.

Option menu

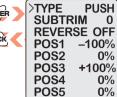












C3: -·····I·····+

[CH3, CH4]

settings for 3 and 4 channel radio control.

>TYPE:

PUSH(*1), 2~5WAY(switches POS by pressing), STmix(for steering mixing *2), THmix(for throttle mixing *2)

>SUBTRIM:-80~ OFF ~+80

>REVERSE: OFF, ON

>POS1~5 (*3):-100~ OFF ~+100

- 1. POS2 and POS3 will be applied during holding function key allocated with "3.POS". POS1 will be applied while not holding "3.POS". If BT key is allocated, press BT key to apply POS2.
- *2. STmix adjusts neutral position.
- **%3.** When STmix is applied, LCD indicates RIGHT, TRIM and LEFT. When THmix is applied, LCD indicates BRAKE, TRIM and HPOINT.



Choose with $[(\bigcirc)]$, set with $[\bigcirc)$

To reset values press both [(+) (-)] for a second

- *If setting is changed during TYPE: PUSH and/or 2-5WAY, POS1 will be applied.
- *Before allocating function key (refer to [Set up] in P26) and TYPE: PUSH and/or 2-5WAY is applied, neutral pulse is generated. Please be careful when installing servo.

Mixing (STmix / THmix)

- 1. Set [Response] in DD:NORM or PP:NORM.
- 2. Set THmix (OP>CH3>TYPE). Throttle trigger mixing will be applied.
- 3. Set CH3 (OP>CH3>SUBTRIM).
- 4. Set maximum brake output of throttle trigger (OP>CH3>BRAKE).
- 5. Set neutral output of throttle trigger (OP>CH3>TRIM), (Keep TRIM between BRAKE and HPOINT.)
- **6.** Set maximum throttle output (forward) of throttle trigger (OP>CH3>HPOINT).
- 7. Set neutral output of throttle trigger (OP>CH3>TRIM). (Keep TRIM between BRAKE and HPOINT.)

CH4 >RSP DD:NORM **INPUT OptionMenu**



(Response) chooses response mode. (NORM, HSP, ADV, Mini-z, Digital)

Choose with [(



], set with [\oplus \ominus]

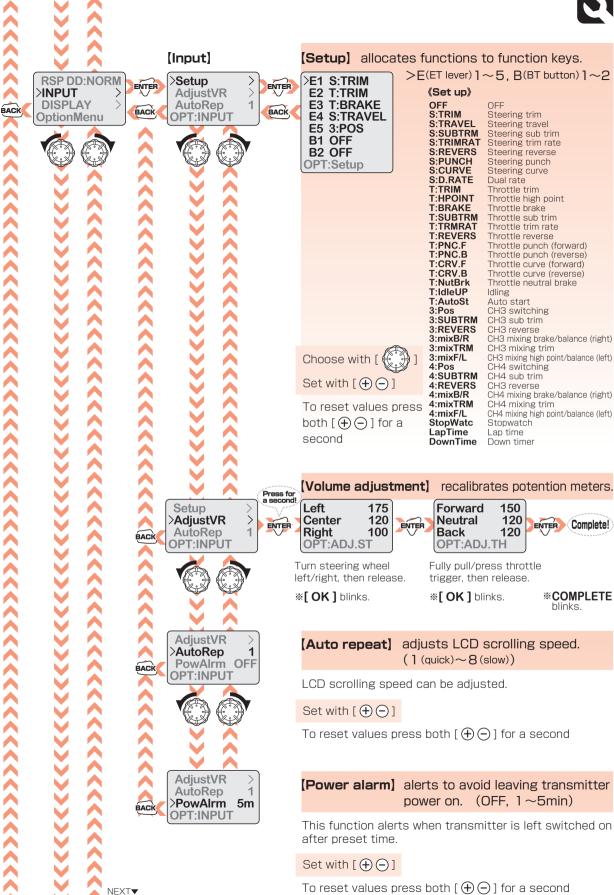
Complete with [ENTER] (return)

| Module | Option |
|---|---------------------------------------|
| D.D.(Direct Digital) compatible modules (RF-902S) | DD:NORM / DD:HSP / DD:ADV |
| D.D.(Direct Digital) compatible modules for Mini-z (RF-902SM) | Mini-z |
| Other modules (for Helios module, etc.) | PP:NORM / PP:HSPD / PP:ADV / Digital* |

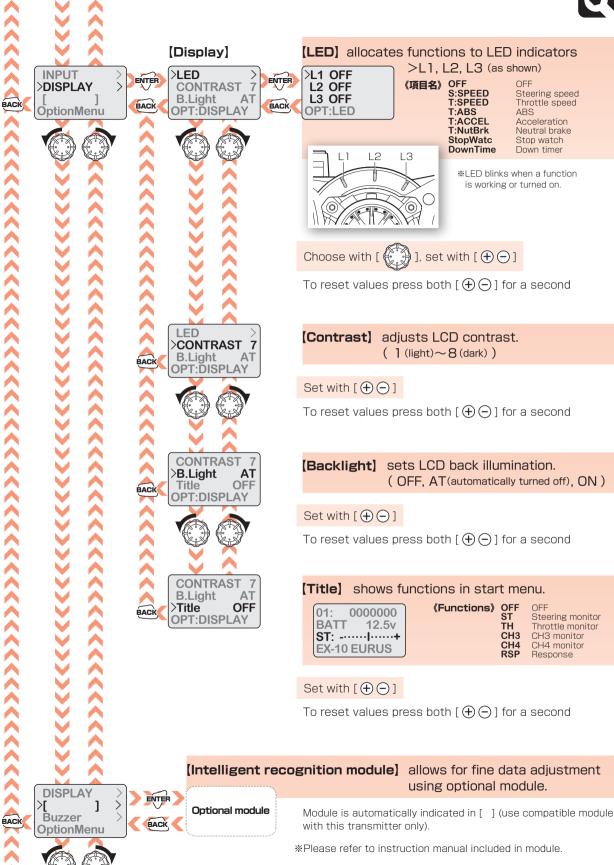
**Press both [(+)(-)] keys to choose Digital mode.

Caution! CH3 and CH4 are not available when choosing DD:HSPD or DD:ADV.



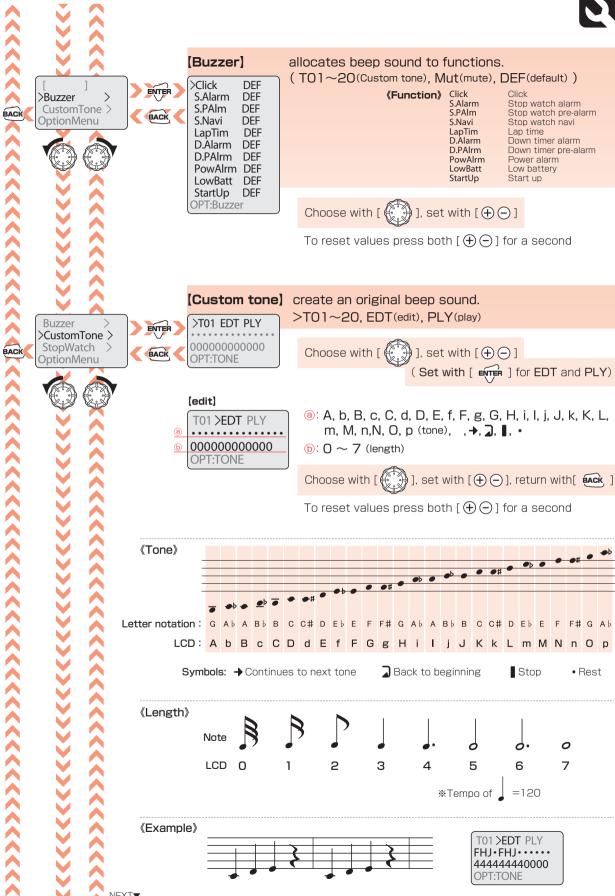






NEXT▼





NEXT▼



| | Š | | | | |
|--|---------------------------------------|--|--------------|--|---|
| BACK | Custon >StopW Down T OptionN | atch Fimer | ENTER DEACK | Stop watch KEY OFF LAP.KEY OFF TH.Start > LAPTIME ALARM OFF P.ALM OFF Navi OFF OP:StopWatch | stop-watch and lap time record function. >KEY(allocates stop-watch function key): OFF, ET1~5, BT1~2 >LAP.KEY(allocates lap time function key): OFF, ET1~5, BT1~2 *1 >TH.Start(starts timing with throttle on.) *2 >LAPTIME(indicates lap time): with [ENTER] >ALARM(alarm): OFF, 0~99min >P.ALM(pre-alarm): OFF, 1~30sec >Navi(periodical timer): OFF, 00m01s~99m59s |
| >>>>> | | ************************************* | 33377 | | Choose with [⊕ ☐], set with [⊕ ☐] To reset values press both [⊕ ☐] for a second |
| ***** | ***** | ****** | ** | Stop watch CustomTone S 00 "00 '00 Dówn "Third!" OptionMenu | [⊕] starts and restarts [⊝] stops [⊝] resets (press for a second) |
| ******** | ****** | ********** | * 1 ENTER | TH.Start] LAP.KEY OFF * R E A D Y LKMYMEY IN OP:StopWatch | Starts timing with throttle on [|
| \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\ | >>>>>>> | ·>>>>>>>> | *2 ENTER | [LAPTIME] TH.Start > >LAPTIME > ALARM OFF OP:StopWatch | Lap time can be recorded by pressing allocated key with LAP.KEY while stop-watch function is working. [ENTER] indicates lap time [EACK] returns To reset values press both [①] for a second **100 lap times can be recorded. |
| | >>>> | **** | <u>\</u> | | X 100 tap times dan be recorded. |
| BACK | Custon StopWa >Down | atch Timer | ENTER | Time 5m00s KEY OFF P.ALM OFF OP:Down Timer | sets countdown timer function. >Time(starts countdown from) : OFF, 00m01s \sim 99m59s >KEY(allocates function key) : OFF, ET1 \sim 5, BT1 \sim 2 >P.ALM (pre-alarm) : OFF, 1 \sim 30sec |
| | | | | | Choose with [⊕ □] To reset values press both [⊕ □] for a second |
| | | | 3 >>> | [Down timer] CustomTone > StopWatch > >D 00 "00 '00 > OptionMend' | [⊕] starts and restarts [⊝] stops [⊝] resets (press for a second) |



■ Transmitter: KT-409H

Operating system: steering wheel & throttle trigger

Number of channels: 4

Transmit frequency band: entire frequency band (using high frequency module)

Neutral pulse: 1.5mSec

Power source: R6/AA/UM3 battery x 8, or 8 cell battery pack **Current consumption**: approx. 80mAh (excl. high frequency band)

■ High frequency module: RF-902S

Modulation: DS-SS

Transmit frequency: 2.4GHz

■ Receiver: KR-409S

Modulation: DS-SS
Number of channels: 4

Received frequency : 2.4GHzOperating voltage : 4.8V-7.4VDimensions : $28\times18.3\times18.5\text{mm}$

Weight: 7.5g

Manufacturer : KONDO KAGAKU CO.,LTD. 116-0014

4-17-7 Higashi-Nippori, Arakawa-ku, Tokyo Japan



If you have any problem, please contact to our distributor in your country. The distributor in your country is listed on our web site under the English information page.

www.kopropo.co.jp

